



Termgraph rewriting for implementing the λ -calculus refactored (WiP)

Vincent van Oostrom & Clemens Grabmayer

Part I: Implementing closed β by orthogonal TRS ($\odot$)

Part II: Implementing $\odot$ through termgraphs $G\odot$

Part III : Implementing β through $G\odot$

Running example (from $\lambda\beta$ -calculus)

Example (2^2)

- Church numeral 2 $:= \lambda sz.s (s z)$

Running example

Example (2^2)

- $\underline{2} := \lambda sz.s(s z)$
- application of Church numerals is **exponentiation**: $\underline{k} \underline{n} \rightarrow_{\beta} \underline{n^k}$

Running example

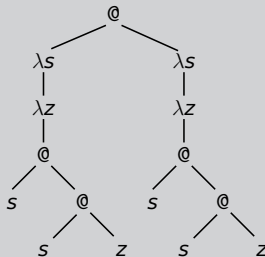
Example (2^2)

- $\underline{2} := \lambda sz.s(s z)$
- $\underline{2} \underline{2} = (\lambda sz.s(s z)) \underline{2} \rightarrow_{\beta} \lambda z.\underline{2}(\underline{2} z) =_{\alpha} \lambda s'.(\lambda sz.s(s z))(\underline{2} s') \rightarrow_{\beta}$
 $\lambda s'z.\underline{2} s'(\underline{2} s' z) =_{\alpha} \lambda sz.\underline{2} s(\underline{2} s z) \twoheadrightarrow_{\beta} \lambda sz.\underline{2} s(s(s z)) \twoheadrightarrow_{\beta} \lambda sz.s(s(s(s z))) =: \underline{4}$

Running example

Example (2^2)

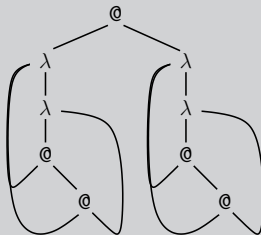
- $\underline{2} := \lambda sz.s(sz)$
- $\underline{2}\underline{2} \rightarrow_{\beta} \underline{2}^2 =: \underline{4} =: \lambda sz.s(s(s(sz)))$
- abstract **syntax** tree of $\underline{2}\underline{2}$:



Running example

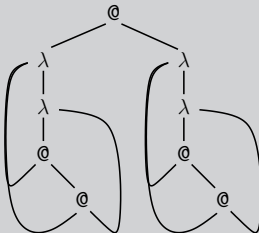
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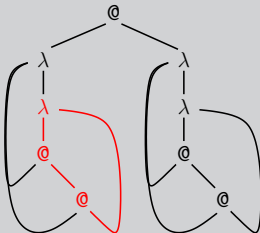
Wadsworth refactored through term rewriting; idea

Example (skeleton of anonymous function $\mapsto$ named function)



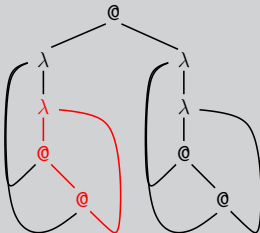
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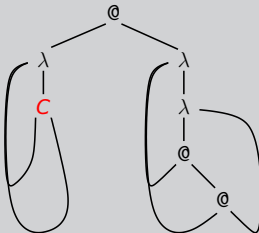
Example (**skeleton** of anonymous function $\mapsto$ named function)



function symbol C with TRS rule $\varrho_C : @ (C(x_1, x_2), x_0) \rightarrow x_1 (x_2 x_0)$

Wadsworth refactored through term rewriting; idea

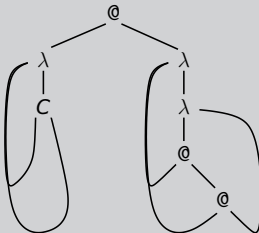
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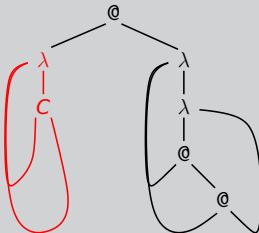
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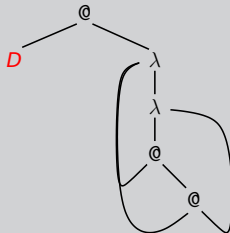
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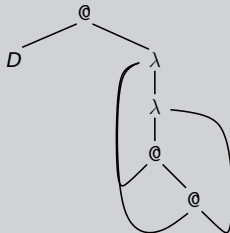


function symbol C with TRS rule $\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$

function symbol D with TRS rule $\varrho_D : D x_0 \rightarrow C(x_0, x_0)$

Wadsworth refactored through term rewriting; idea

Example (skeleton of anonymous function $\mapsto$ named function)

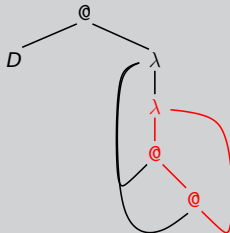


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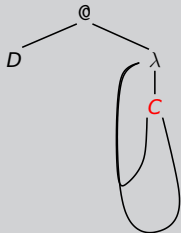


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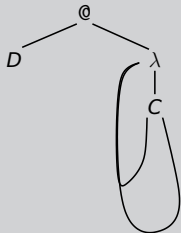
function symbol C with TRS rule $\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$

(reuse)

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Wadsworth refactored through term rewriting; idea

Example (skeleton of anonymous function $\mapsto$ named function)

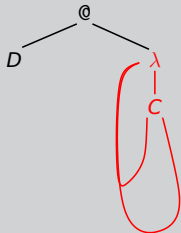


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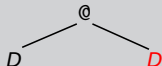


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Example (skeleton of anonymous function $\mapsto$ **named function)**



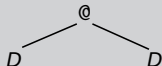
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Compiling a λ -term into a term in a TRS

Definition ($\odot$ maps a λ -term M to pair $(\mathcal{R}, t)$ of TRS $\mathcal{R}$ and term t in it)

- $(x)_{\odot} := (\emptyset, x)$
- $(M_1 M_2)_{\odot} := (\mathcal{R}_1 \cup \mathcal{R}_2, t_1 t_2)$, where $(\mathcal{R}_i, t_i) := (M_i)_{\odot}$ for $i \in \{1, 2\}$
- $(\lambda x. M)_{\odot} := (\{\varrho_C : C(z_1, \dots, z_n) x \rightarrow r[z_1, \dots, z_n]\} \cup \mathcal{R}, C(t_1, \dots, t_n))$, where $(\mathcal{R}, r[t_1, \dots, t_n]) := (M)_{\odot}$, r **skeleton**, t_i **maximal x -free** subterm occurrences

do allow components to **share** constructors when these have the same rules
compilation standard variation on **abstraction algorithm** (custom combinators)

Compiling a λ -term into a term in a TRS

Definition ($\odot$ -lifting; Hughes 82)

- $(x)_{\odot} := (\emptyset, x)$
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Example

$(\underline{2} \underline{2})_{\odot} := (\{\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0), \varrho_D : D x_0 \rightarrow C(x_0, x_0)\}, D D)$
since $(\underline{2})_{\odot} := (\{\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0), \varrho_D : D x_0 \rightarrow C(x_0, x_0)\}, D)$

Compiling a λ -term into a term in a TRS

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$$(\underline{2} \underline{2})_{\odot} := (\{\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0), \varrho_D : D x_0 \rightarrow C(x_0, x_0)\}, D D)$$

Example

$$\underline{2} \underline{2} \rightarrow_{\beta} \lambda z. \underline{2} (\underline{2} z) \text{ implemented by } \textcolor{red}{D} \textcolor{red}{D} \rightarrow_{\varrho_D} C(D, D)$$

Standard example: compiling combinators

Example (combinators in the λ -calculus)

$$\mathcal{I} := \lambda x.x \quad \mathcal{K} := \lambda x y.x \quad \mathcal{S} := \lambda x y z.x z (y z)$$

eye-lifting of $\mathcal{I} \mathcal{K} \mathcal{S}$?

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Example (combinators in the λ -calculus)

$$\mathcal{I} := \lambda x.x \quad \mathcal{K} := \lambda x y.x \quad \mathcal{S} := \lambda x y z.x z (y z)$$

$(\mathcal{I} \mathcal{K} \mathcal{S})_{\odot} := (\mathcal{R}, IKS)$ where $\mathcal{R}$ has rules:

$$\begin{array}{ll} \varrho_{S_2} : S_2(x_1, x_2) x_0 \rightarrow (x_1 x_0) (x_2 x_0) & \varrho_{K_1} : K_1(x_1) x_0 \rightarrow x_1 \\ \varrho_{S_1} : S_1(x_1) x_0 \rightarrow S_2(x_1, x_0) & \varrho_K : K x_0 \rightarrow K_1(x_0) \\ \varrho_S : S x_0 \rightarrow S_1(x_0) & \varrho_I : I x_0 \rightarrow x_0 \end{array}$$

flat Combinatory Logic (CL^b); Asperti & Laneve 96, Goncharov & coauthors 24. . .
idea: first collect sufficiently many arguments, then reduce to right-hand side

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Example

$\mathcal{I} \mathcal{K} \mathcal{S} \rightarrow_{\beta} \mathcal{K} \mathcal{S} \rightarrow_{\beta} \lambda y. \mathcal{S}$ implemented by $IKS \rightarrow_{\varrho_I} KS \rightarrow_{\varrho_K} K_1(S)$

Implementation of β ?

Question

What is an **implementation**?

preciously little literature on that (but *cf.*, *e.g.*, Sabry & Wadler); **go for it!**

Implementation of β ?

Definition

implementation is an **isomorphism** of rewrite systems

unrealistically strong, but **a** starting point

Implementation of β ?

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implementation is an isomorphism of rewrite systems

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β -reduction graph of M **isomorphic** to $\mathcal{R}$ -reduction graph of t , for $(\mathcal{R}, t) := (M)_{\odot}$?

Implementation of β ?

Definition

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β -reduction graph of M isomorphic to $\mathcal{R}$ -reduction graph of t , for $(\mathcal{R}, t) := (M)_{\odot}$?

Example (no!)

$M = \lambda x. \mathfrak{I} x \rightarrow_{\beta} \lambda x. x =: \mathfrak{I}$

$t := C$ in normal form for $\mathcal{R} := \{\varrho_I : I x_0 \rightarrow x_0, \varrho_C : C x_0 \rightarrow I x_0\}$

Implementation of β ?

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β -reduction graph of M isomorphic to $\mathcal{R}$ -reduction graph of t , for $(\mathcal{R}, t) := (M)_{\odot}$?

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t in normal form for any closed M of shape $\lambda x. N(x)$; cf. **abstraction** algorithm
intuition: nameless $\mapsto$ named implementation **hides** non-free redexes from view

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is **closed** β : no variable **in** redex **bound above** it (Çagman & Hindley, Mackie. . .)

for **programs** (no free variables) all $\bar{\beta}$ -redexes **are** indeed **closed**

Example

$\lambda x. \lambda x. x$ is in $\bar{\beta}$ -normal form since x (free) in β -redex $\lambda x. x$ and bound above it (by λx)
 $\lambda x. \lambda x. x$ has $\bar{\beta}$ -redex occurrence $\lambda x. x$

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is closed β : no variable in redex bound above it

$\bar{\beta}$ needs no (α -)renaming; no variables in argument $\implies$ no variable capture
(motivation for usage of $\bar{\beta}$ in functional programming; Peyton Jones)

$\bar{\beta}$ suffices for computing values (CbN / Haskell, CbV / OCAML)

$\bar{\beta}$ -normal forms 1st approximations to normal forms in type-checking (Automath)

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is closed β : no variable in redex bound above it

Example ($\bar{\beta}$ is well-behaved)

$\lambda y.\mathcal{I} \bar{\beta} \leftarrow \lambda y.\mathcal{I} \mathcal{I} \bar{\beta} \leftarrow \mathcal{K}(\mathcal{I} \mathcal{I}) \rightarrow_{\bar{\beta}} \mathcal{K} \mathcal{I} \rightarrow_{\bar{\beta}} \lambda y.\mathcal{I}$ (unique normal form)

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is closed β : no variable in redex bound above it

Example ($\bar{\beta}$ is well-behaved)

$$\lambda y.\mathcal{I} \bar{\beta} \leftarrow \lambda y.\mathcal{I} \mathcal{I} \bar{\beta} \leftarrow \mathcal{K}(\mathcal{I} \mathcal{I}) \rightarrow_{\bar{\beta}} \mathcal{K} \mathcal{I} \rightarrow_{\bar{\beta}} \lambda y.\mathcal{I}$$

Lemma

$\bar{\beta}$ is confluent

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is closed β : no variable in redex bound above it

Lemma (👁-lifting)

if $M \rightarrow_{\bar{\beta}} N$ and $(t, \mathcal{R}) := (M)_{\text{👁}}$ then $t \rightarrow_{\mathcal{R}} s$ for some $(s, \mathcal{S}) := (N)_{\text{👁}}$ with $\mathcal{R} \supseteq \mathcal{S}$

only $\supseteq$ because redexes may be erased and constructors **shared** in compilation
closed redex **nested** in another redex is **free** in it, so a **parameter** in compilation
to **formalise** use **higher-order** term rewriting (combines λ with TRS)

Implementation of $\bar{\beta}$

Definition

$\bar{\beta}$ is closed β : no variable in redex bound above it

Corollary

homomorphism from $\bar{\beta}$ -reduction from M to $\mathcal{R}$ -reduction from t for $(t, \mathcal{R}) := (M)_{\odot}$

Implementation of $\bar{\beta}$

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homomorphism from $\bar{\beta}$ -reduction from M to $\mathcal{R}$ -reduction from t for $(t, \mathcal{R}) := (M)_{\odot}$

what about **de**compilation?

Decompiling a term in a TRS into a λ -term

Definition (decompilation $(t)_\lambda$ homomorphism)

$C_i(t_1, \dots, t_n) \mapsto (\lambda x_0. (r)_\lambda)[x_1, \dots, x_n := t_1, \dots, t_n]$ for rule $C_i(x_1, \dots, x_n) x_0 \rightarrow r$ in $\mathcal{R}$

capture avoiding substitution (avoiding capture of free variables of the t_k)

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Example (running; decompiling Church numeral 2)

$$\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$

$$C(t_1, t_2) \mapsto \lambda x_0. t_1 (t_2 x_0)$$

$$\varrho_D : D x_0 \rightarrow C(x_0, x_0)$$

$$D \mapsto \lambda x_0 x'_0. x_0 (x_0 x'_0) =_{\alpha} \underline{2}$$

$$\text{i.e. } D \mapsto \lambda x_0. (C(x_0, x_0))_\lambda = \lambda x_0. (\lambda x_0. x_1 (x_2 x_0))[x_1, x_2 := x_0, x_0] =_{\alpha} \lambda x_0 x'_0. x_0 (x_0 x'_0)$$

Decompiling a term in a TRS into a λ -term

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Example (running; decompiling Church numeral $\underline{2}$)

$$\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$

$$C(t_1, t_2) \mapsto \lambda x_0. t_1 (t_2 x_0)$$

$$\varrho_D : D x_0 \rightarrow C(x_0, x_0)$$

$$D \mapsto \lambda x_0 x'_0. x_0 (x_0 x'_0) =_\alpha \underline{2}$$

$$(DD)_\lambda = \underline{2} \underline{2}$$

both $((\underline{2} \underline{2})_\odot)_\lambda =_\alpha \underline{2} \underline{2}$ and $((DD)_\lambda)_\odot = DD$ up to **naming** combinators

Decompiling a term in a TRS into a λ -term

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Example (decompiling combinators)

$$\begin{array}{ll} \varrho_{S_2}: S_2(x_1, x_2) x_0 \rightarrow (x_1 x_0) (x_2 x_0) & S_2(t_1, t_2) \mapsto \lambda x_0. (t_1 x_0) (t_2 x_0) \\ \varrho_{S_1}: S_1(x_1) x_0 \rightarrow S_2(x_1, x_0) & S_1(t_1) \mapsto \lambda x_0 x'_0. (t_1 x'_0) (x_0 x'_0) \\ \varrho_S: S x_0 \rightarrow S_1(x_0) & S \mapsto \lambda x_0 x'_0 x''_0. (x_0 x''_0) (x'_0 x''_0) =_\alpha \mathfrak{S} \\ \varrho_{K_1}: K_1(x_1) x_0 \rightarrow x_1 & K_1(t_1) \mapsto \lambda x_0. t_1 \\ \varrho_K: K x_0 \rightarrow K_1(x_0) & K \mapsto \lambda x_0 x'_0. x_0 =_\alpha \mathfrak{K} \\ \varrho_I: I x_0 \rightarrow x_0 & I \mapsto \lambda x_0. x_0 =_\alpha \mathfrak{I} \end{array}$$

both $((\mathfrak{I} \mathfrak{K} \mathfrak{S})_{\odot})_\lambda =_\alpha \mathfrak{I} \mathfrak{K} \mathfrak{S}$ and $((IKS)_\lambda)_{\odot} = IK S$ up to naming combinators

Decompiling a term in a TRS into a λ -term

Definition (decompilation $(t)_\lambda$ homomorphism)

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Definition (applicative inductive interaction TRS, **aij**,)

$\varrho_C : C(x_1, \dots, x_{n_C}) x_0 \rightarrow r$ with r built from $@$, $\vec{x}$ and $< C$ (well-founded $<$)

assume r **linear** in $x_1, \dots, x_{n_C}$ preserving tree-**order** (x_0 may be **replicated**)

applicative since application $@$ **only** destructor

inductive since right-hand side r constructed from **smaller** constructors

interaction (Asperti & Laneve) since left-hand sides **destructor-constructor**

Decompiling a term in a TRS into a λ -term

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Definition (applicative inductive interaction TRS, aij , $\odot$)

$\varrho_C : C(x_1, \dots, x_{n_C}) x_0 \rightarrow r$ with r built from $\odot$, $\vec{x}$ and $< C$ (well-founded $<$)

Example

Church numeral: $C < D$

combinators: $K_1 < K$ and $S_2 < S_1 < S$

Decompiling a term in a TRS into a λ -term

Definition (decompilation $(t)_\lambda$ homomorphism)

$C_i(t_1, \dots, t_n) \mapsto (\lambda x_0. (r)_\lambda)[x_1, \dots, x_n := t_1, \dots, t_n]$ for rule $C_i(x_1, \dots, x_n) x_0 \rightarrow r$ in $\mathcal{R}$

Definition (applicative inductive interaction TRS, aij , $\odot$)

$\varrho_C : C(x_1, \dots, x_{n_C}) x_0 \rightarrow r$ with r built from $@$, $\vec{x}$ and $< C$ (well-founded $<$)

Theorem (implementation)

$((M)_{\odot})_\lambda =_\alpha M$ for any λ -term M and $((t)_\lambda)_{\odot} = t$ for any $\odot$ -term t (up to naming)
if $t \rightarrow_{\odot} s$ then $(t)_\lambda \rightarrow_{\vec{\beta}} (s)_\lambda$ and if $M \rightarrow_{\vec{\beta}} N$ then $(t)_{\odot} \rightarrow_{\odot} (s)_{\odot}$

$(t[\vec{x} := \vec{t}])_\lambda = (t)_\lambda[\vec{x} := (\vec{t})_\lambda]$ (substitution lemma)

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Example

$D(D z_1) \rightarrow_{\odot} C(D z_1, D z_1)$ by rule $\varrho_D : D x_0 \rightarrow C(x_0, x_0) \iff$
 $(D(D z_1))_\lambda = (\lambda xy. x (x y)) (\underline{2} z_1) \rightarrow_{\bar{\beta}} \lambda y. \underline{2} z_1 (\underline{2} z_1 y) =_\alpha (C(D z_1, D z_1))_\lambda$

Decompiling a term in a TRS into a λ -term

Definition (decompilation $(t)_\lambda$ homomorphism)

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Corollary (implementation of $\bar{\beta}$ by $\odot$)

isomorphism between $\bar{\beta}$ -reduction from M , $\mathcal{R}$ -reduction from t , for $(t, \mathcal{R}) := (M)_{\odot}$

Functional programming theory is TRS theory (not λ)

Idea (reductionist)

reduce the theory of closed β -reduction to that of -reduction

( 05)

Functional programming theory is TRS theory

Idea (reductionist)

reduce the theory of closed β -reduction to that of $\circlearrowright$ -reduction

($\circlearrowright$ 05)

Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? (**weak** β ; redex **not below** a λ)

$$\lambda y. \mathcal{I} \mathcal{I} \xrightarrow{\tilde{\beta}} \mathcal{K}(\mathcal{I} \mathcal{I}) \rightarrow_{\tilde{\beta}} \mathcal{K} \mathcal{I} \rightarrow_{\tilde{\beta}} \lambda y. \mathcal{I} \quad (\text{distinct } \tilde{\beta}\text{-normal forms})$$

Functional programming theory is TRS theory

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reduce the theory of closed β -reduction to that of $\circlearrowleft$ -reduction

($\circlearrowleft$ 05)

Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? $\tilde{\beta}$ **sub**system of $\bar{\beta}$ ($\circlearrowleft$ of $\circlearrowleft$: **not below** constructor)
 $\lambda y.\tilde{\mathcal{I}} \tilde{\beta} \leftarrow \lambda y.\tilde{\mathcal{I}} \tilde{\mathcal{I}} \tilde{\beta} \leftarrow \mathcal{K}(\tilde{\mathcal{I}} \tilde{\mathcal{I}}) \rightarrow_{\tilde{\beta}} \mathcal{K} \tilde{\mathcal{I}} \rightarrow_{\tilde{\beta}} \lambda y.\tilde{\mathcal{I}}$ (**same** $\bar{\beta}$ -normal form)

Functional programming theory is TRS theory

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($\circlearrowright$ 05)

Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? $\tilde{\beta}$ subsystem of $\bar{\beta}$ ($\circlearrowright$ subsystem of $\circlearrowright$)
- $\bar{\beta}$ confluent?

Functional programming theory is TRS theory

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Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? $\tilde{\beta}$ subsystem of $\bar{\beta}$ ($\circlearrowright$ subsystem of $\circlearrowright$)
- $\bar{\beta}$ confluent? because $\circlearrowright$ is **orthogonal** (**left-linear** and **non-overlapping**)

Functional programming theory is OTRS theory

Idea (reductionist)

reduce the theory of closed β -reduction to that of $\odot$ -reduction

($\odot$ 05)

Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? $\tilde{\beta}$ subsystem of $\bar{\beta}$ ($\tilde{\odot}$ subsystem of $\odot$)
- $\bar{\beta}$ confluent? because $\odot$ is orthogonal (OTRS)
- **leftmost-outermost** (**lmo**) strategy (hyper-)((weak-)head-)normalising?

Functional programming theory is OTRS theory

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- Imo strategy (hyper-)((weak-)head-)normalising? as $\circlearrowleft$ is **left-normal** OTRS

Functional programming theory is OTRS theory

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- Imo strategy (hyper-)((weak-)head-)normalising? as $\odot$ is left-normal OTRS
- **termgraph** implementation of $\bar{\beta}$?

Functional programming theory is OTRS theory

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- Imo strategy (hyper-)((weak-)head-)normalising? as $\odot$ is left-normal OTRS
- termgraph implementation of $\bar{\beta}$? through **termgraph** implementation of $\odot$
here: Wadsworth's termgraph implementation of $\bar{\beta}$ **refactored** through
known termgraph implementation of OTRS (e.g., Staples 80s)

Functional programming theory is OTRS theory

Idea (reductionist)

reduce the theory of closed β -reduction to that of $\circlearrowleft$ -reduction

($\circlearrowleft$ 05)

Example (some TRS theory that $\bar{\beta}$ theory can be reduced to)

- isn't FP theory about $\tilde{\beta}$? $\tilde{\beta}$ subsystem of $\bar{\beta}$ ($\tilde{\circlearrowleft}$ subsystem of $\circlearrowleft$)
- $\bar{\beta}$ confluent? because $\circlearrowleft$ is orthogonal (OTRS)
- Imo strategy (hyper-)((weak-)head-)normalising? as $\circlearrowleft$ is left-normal OTRS
- termgraph implementation of $\bar{\beta}$? through termgraph implementation of $\circlearrowleft$
- standardisation, external, needed, strategies, ...

Simply typing (reductionist)

Definition (simply typed)

$C : (\vec{\tau}) \rightarrow \tau \rightarrow \sigma$ if infer $\vec{X} : \vec{\tau}, x_0 : \tau \vdash r : \sigma$ for $\varrho_C : C(x_1, \dots, x_n) x_0 \rightarrow r$

type **schemata** as usual

types of constructors defined by **recursion** via $<$; $@ : ((\tau \rightarrow \sigma) \times \tau) \rightarrow \sigma$ as usual
 $(\vec{\tau})$ **product** type with length **arity** of C ; by convention τ denotes $() \rightarrow \tau$ as usual

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Example (D ; compilation of Church numeral 2)

$C : ((v \rightarrow \sigma) \times (\tau \rightarrow v)) \rightarrow \tau \rightarrow \sigma$ since $x_1 : v \rightarrow \sigma, x_2 : \tau \rightarrow v, x_0 : \tau \vdash x_1 (x_2 x_0) : \sigma$

$D : (\sigma \rightarrow \sigma) \rightarrow \sigma \rightarrow \sigma$ since $x_0 : \sigma \rightarrow \sigma \vdash C(x_0, x_0) : \sigma \rightarrow \sigma$ and by convention

$D : ((\sigma \rightarrow \sigma) \rightarrow \sigma \rightarrow \sigma) \rightarrow (\sigma \rightarrow \sigma) \rightarrow \sigma \rightarrow \sigma$ for left D in compilation DD of 2

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Example (simply typed CL^b (xTCL in Goncharov & al. 24))

- $I : \sigma \rightarrow \sigma$ since $x_0 : \sigma \vdash x_0 : \sigma$ and by convention
- $K_1 : (\sigma) \rightarrow \tau \rightarrow \sigma$ since $x_1 : \sigma, x_0 : \tau \vdash x_1 : \sigma$
- $K : \sigma \rightarrow \tau \rightarrow \sigma$ since $x_0 : \sigma \vdash K_1(x_0) : \tau \rightarrow \sigma$ and by convention
- $S_2 : (\tau \rightarrow v \rightarrow \sigma) \times (\tau \rightarrow v) \rightarrow \tau \rightarrow \sigma$ since
$$x_1 : \tau \rightarrow v \rightarrow \sigma, x_2 : \tau \rightarrow v, x_0 : \tau \vdash (x_1 x_0) (x_2 x_0) : \sigma$$
- $S_1 : (\tau \rightarrow v \rightarrow \sigma) \rightarrow (\tau \rightarrow v) \rightarrow \tau \rightarrow \sigma, x_1 : \tau \rightarrow v \rightarrow \sigma, x_0 : \tau \rightarrow v \vdash S_2(x_1, x_0) : \tau \rightarrow \sigma$
- $S : (\tau \rightarrow v \rightarrow \sigma) \rightarrow (\tau \rightarrow v) \rightarrow \tau \rightarrow \sigma$ as $x_0 : \tau \rightarrow v \rightarrow \sigma \vdash S_1(x_0) : (\tau \rightarrow v) \rightarrow \tau \rightarrow \sigma$

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Lemma

simply typed  is terminating and simply typedness preserved by compilation

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Definition (strongly computable (**SC**; Tait, Girard))

t is **SC** if $t \vec{s}$ is terminating for all SC terms $\vec{s}$

SC **inductive** since $\vec{s}$ have types **smaller** than t

SC $\implies$ terminating (take $\vec{s}$ the **empty** vector)

application $t v$ is SC if subterms t and v both are SC (by **rebracketing**)

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Lemma

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Proof.

sufficient to show $h := C(\vec{t})$ is SC if $\vec{t}$ are SC.

Simply typing (reductionist)

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sufficient to show $h := C(\vec{t})$ is SC if $\vec{t}$ are SC. by induction on C ordered by $<$.
 $h \vec{s} \twoheadrightarrow h' \vec{s}' = C(\vec{x}^{\zeta'}) x_0^{\zeta'} \vec{v}' \rightarrow r^{\zeta'} \vec{v}' \rightarrow \dots$ shape of ∞ reduction for rule $C(\vec{x}) x_0 \rightarrow r$.

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$h \vec{s} = C(\vec{x}^{\zeta}) x_0^{\zeta} \vec{v} \rightarrow r^{\zeta} \vec{v} \twoheadrightarrow r^{\zeta'} \vec{v}'$ for some $\zeta, \vec{v}$ and $r^{\zeta} \vec{v}$ SC by IH so terminating $\nexists$ $\square$

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Remark (Goncharov & al. 24 on their new proof of termination of xTCL)

The reader should compare the above compact argument to the laborious original proof given in Example 15

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marketing trick: first **raise** the price to then advertise a **discount**?

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techniques interesting; apply to ; suggest cross-fertilisation with PRS theory

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Summary of Part I: Implementing closed β by orthogonal TRS ()

functional programming theory reduces to OTRS () theory

OTRS theory (trees, substitution, algebra) simpler than theory for λ (binding ...)

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what about implementation of OTRS / .

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Summary of Part I: Implementing closed β by orthogonal TRS ()

functional programming theory reduces to OTRS () theory

OTRS theory (trees, substitution, algebra) simpler than theory for λ (binding ...)

what about implementation of OTRS / ? up next

idea: **factor** through **termgraph** implementation of  **horizontal** sharing; dags

Why OTRSs not a convincing model of computation?

Quote (Computability and λ -definability; Turing 37)

The identification of 'effectively calculable' functions with computable functions is possibly more convincing than an identification with the λ -definable or general recursive functions.

Why OTRSs not a convincing model of computation?

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The identification of 'effectively calculable' functions with computable functions is possibly more convincing than an identification with the λ -definable or general recursive functions.

My perspective

all (also OTRSs) are fine for **effectivity** (**whether**), not for **efficiency** (**complexity**) due to **implicit replication**. Turing Machines have **convincing unit-time** steps.

TMs are **sequential** others **causal** (**asynchronous**) models of computations

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My perspective

all (also OTRSs) are fine for effectivity (whether), not for efficiency (complexity) due to implicit replication. Turing Machines have convincing unit-time steps.

Plan for Part II: Implementing $\textcircled{\text{e}}$ through termgraphs $G\textcircled{\text{e}}$ (Staples 80s)

argue termgraphs ($G\textcircled{\text{e}}$) have **convincing** unit-time steps. compile $\textcircled{\text{e}}$ to $G\textcircled{\text{e}}$ with steps implementing contraction of **family** of $\textcircled{\text{e}}$ -redex-patterns (**shared** in $G\textcircled{\text{e}}$).

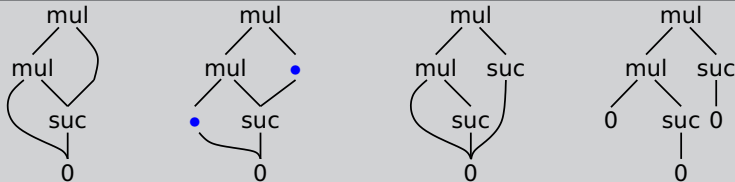
Termgraphs revisited

Termgraphs revisited

Definition (Termgraph)

finite directed acyclic graph (**dag**) with designated root. nodes labelled by signature extended with **indirection** • of arity 1. node labelled by symbol of arity n has 1 input port (number of in-edges) and n output ports (1 out-edge per port).

Example (four termgraphs for term $\text{mul}(\text{mul}(0, \text{suc}(0)), \text{suc}(0))$)



root implicit as input port without in-edge (here: mul); edges directed downward

Termgraphs revisited

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Notations

$\boxed{t}$ to denote the termgraph of term t (a tree up to sharing of variables)

$\widehat{G}$ to denote the term of termgraph G (reading back from designated root)

mnemonic: terms are triangles $\triangle$ and graphs are squares $\square$

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note $\widehat{\boxed{t}} = t$ for any term t

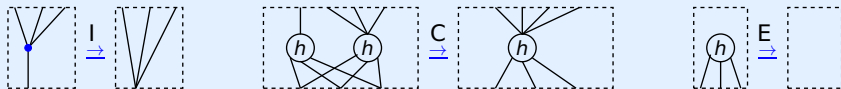
what about the converse? how does $\boxed{\widehat{G}}$ relate to G ?

Termgraphs revisited

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finite directed acyclic graph (dag) with designated root. nodes labelled by signature extended with indirection $\bullet$ of arity 1. node labelled by symbol of arity n has 1 input port (number of in-edges) and n output ports (1 out-edge per port).

Definition ($\mathcal{K}$; zhe, a **substitution-calculus** $\mathbb{V}$ & van Raamsdonk)



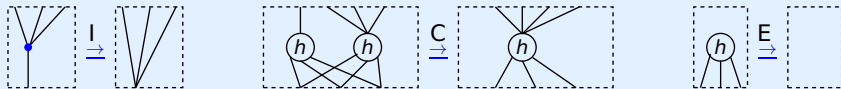
$\rightarrow$ -normal forms **maximally** shared (ATerm); $\leftrightarrow$ denotes equivalence closure of $\rightarrow$
 $G \leftrightarrow H$ iff $\hat{G} = \hat{H}$ (collecting garbage E, unsharing C^{-1} , directing I gives term-tree)

Termgraphs revisited

Definition (Termgraph)

finite directed acyclic graph (dag) with designated root. nodes labelled by signature extended with indirection $\bullet$ of arity 1. node labelled by symbol of arity n has 1 input port (number of in-edges) and n output ports (1 out-edge per port).

Definition ($\mathbb{K}$ SC)



$\rightarrow$ -normal forms maximally shared; $\Leftrightarrow$ denotes equivalence closure of $\rightarrow$

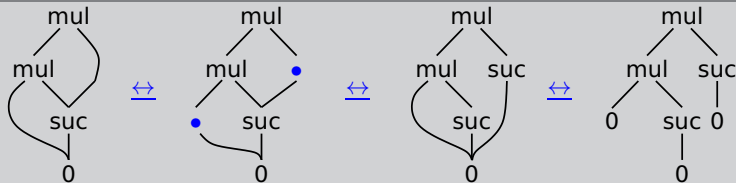
$G \Leftrightarrow H$ iff $\widehat{G} = \widehat{H}$ so $\boxed{\widehat{G}} \Leftrightarrow G$; terms as $\mathbb{K}$ - / $\Leftrightarrow$ -equivalence classes of termgraphs

Termgraphs revisited

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Example (four termgraphs for term $\text{mul}(\text{mul}(0, \text{suc}(0)), \text{suc}(0))$)



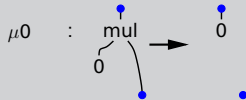
inserting indirections, removing them again and unsharing suc , then unsharing 0

Termgraph rewriting (TGRS) refactored through SC

Definition (TGRS)

rule has source (**lhs**) and target (**rhs**) termgraphs having same **interface**.

Example (of rule $\mu 0 : \text{mul}(0, x_0) \rightarrow 0$)



interface of indirection nodes • corresponding to rule $\mu 0$ having arity 1

TGRS rules **linear**; all **replication** relegated to $\mathbb{K}$

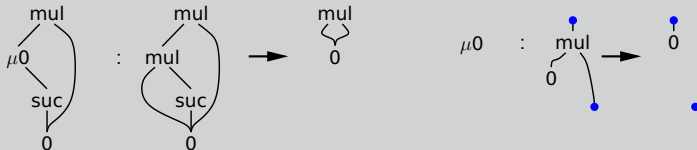
Termgraph rewriting refactored through SC

Definition (TGRS)

rule has source (lhs) and target (rhs) termgraphs having same interface.

step **replaces** lhs by rhs **modulo** $\bowtie$ **substitution calculus** ($\bowtie$ & van Raamsdonk)

Example (of step $\text{mul}(\mu 0(\text{suc}(0)), 0) : \text{mul}(\text{mul}(0, \text{suc}(0))), 0 \rightarrow \text{mul}(0, 0)$ **)**



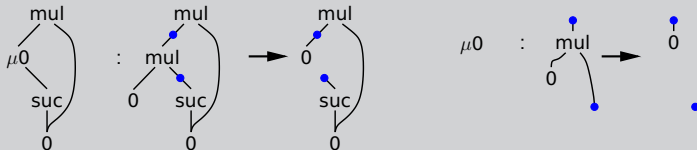
(i) unsharing 0 and inserting •, (ij) $\mu 0$ -replacement, (iij) gc and sharing 0s

Termgraph rewriting refactored through SC

Definition (TGRS)

rule has source (lhs) and target (rhs) termgraphs having same interface.
step replaces lhs by rhs **modulo** $\bowtie$ SC (both in **matching** and **substitution**)

Example (of step $\text{mul}(\mu 0(\text{suc}(0)), 0) : \text{mul}(\text{mul}(0, \text{suc}(0))), 0 \rightarrow \text{mul}(0, 0)$ **)**



(i) unsharing 0 and inserting •, (ij) **$\mu 0$ -replacement**, (iij) gc and sharing 0s

multistep is termgraph over signature + rules (**single** / **parallel** step special case)

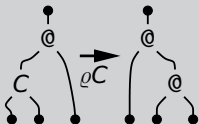
Termgraph rewriting refactored through SC

Definition (TGRS)

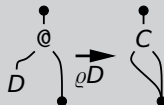
rule has source (lhs) and target (rhs) termgraphs having same interface.
step replaces lhs by rhs modulo $\bowtie$

Example (G_⊙ rules corresponding to ⊙ for Church numeral 2)

$$\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$



$$\varrho_D : D x_0 \rightarrow C(x_0, x_0)$$



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Lemma (implementation of TRS by TGRS)

$\phi : t \rightarrow s$ iff $\Phi : G \rightarrow H$ (*multistep*; unsharing preserves *redex-patterns* in Φ)
 $\phi : t \rightarrow\!\!\rightarrow s$ iff $\Phi : G \rightarrow\!\!\rightarrow H$ (*parallel* step; unsharing preserves *parallelism* in Φ)
for $t = \hat{G}$, $s = \hat{H}$ and $\phi = \hat{\Phi}$

Proof.

by $\bowtie$ -unsharing (multi / parallel) termgraph to (multi / parallel) term-tree □

step $\Phi : G \rightarrow H$ yields *step* $\phi : G \rightarrow H$ only if rule in Φ has *unique access path*

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since TRS not a **convincing** model of computation also TGRS not (by lemma)

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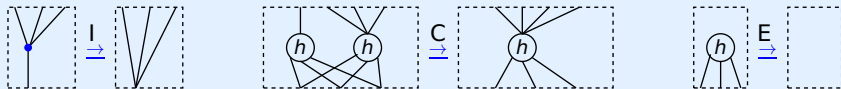
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since TRS not a convincing model of computation also TGRS not
caused by **modulo** $\bowtie$. idea:  are simple so can **largely abstain** from modulo $\bowtie$

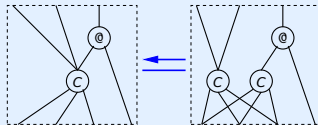
TGRS $G_{\odot}$ by constructor-unsharing (cu)

Definition ($G_{\odot}$ by cu; Wadsworth's **admissibility**)

recall $\Rightarrow$ **rules** gives **maximal sharing** in $\mathcal{K}$:



constructor-unsharing $G_{\odot}$ restricts $\mathcal{K}$ to I, C^{-1} needed to **exhibit** $\odot$ -redexes:

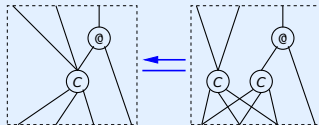


never **unshare** redex-patterns in termgraph G (only constructors of redexes)
sufficient to **exhibit** (all) redex-patterns

TGRS $G\odot$ by constructor-unsharing (cu)

Definition ($G\odot$)

constructor-unsharing $G\odot$ restricts $\mathcal{K}$ to I, C^{-1} needed to exhibit $\odot$ -redexes:



Lemma (shared steps do at least as much)

if $\phi : \hat{G} \rightarrow_{\odot} s$, then $\Phi : G \rightarrow_{G\odot} H$ for some parallel step Φ **extending** ϕ ($\phi \sqsubseteq \hat{\Phi}$)

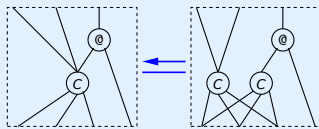
Proof.

exhibit the redex-pattern of ϕ in G to yield Φ . that may be shared however, giving rise to a **parallel** step $\hat{\Phi} : \hat{G} \dashrightarrow_{\odot} v$ for some term v with $s \dashrightarrow_{\odot} v$. □

TGRS $G\odot$ by constructor-unsharing (cu)

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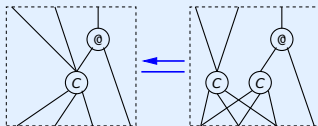
contracting **more is better** in $\odot$ (in any orthogonal TRS)

for R a $G\odot$ -reduction from $\boxed{t}$, parallel $\odot$ -reduction $\hat{R}$ from t is a **family**-reduction

TGRS $G\odot$ by constructor-unsharing (cu)

Definition ($G\odot$)

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Example (family reduction, for simple OTRS)

for $\varrho : f(x) \rightarrow g(x, x)$ and $\vartheta : a \rightarrow b$, there is a **family** reduction

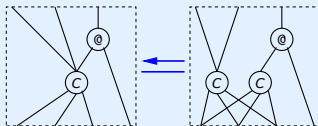
$f(a) \rightarrow\!\!\!\rightarrow g(\mathbf{a}, \mathbf{a}) \rightarrow\!\!\!\rightarrow g(b, b)$ (because both **a**-redex-patterns are **shared**), but

$f(a) \rightarrow\!\!\!\rightarrow g(\mathbf{a}, \mathbf{a}) \rightarrow\!\!\!\rightarrow g(b, a)$ is **not** (it would require **unsharing a**-redex-pattern)

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termgraph rewriting induces **family** reduction on terms (**shared** redex-pattern)

G is convincing model of computation

$G_{\bullet}$ is convincing model of computation

Linear space

a $G_{\bullet}$ -reduction R from $\boxed{t}$ for some term t uses space $O(n)$ after n steps, since the number of symbols introduced by a step of R is bounded by the size of rhss.

constructor-unsharing creates ≤ 1 constructor (and out-edges; removes $\bullet$ s)

$G\circ$ is convincing model of computation

Linear space

a $G\circ$ -reduction R from $\boxed{t}$ for some term t uses space $O(n)$ after n steps, since the number of symbols introduced by a step of R is bounded by the size of rhss.

Pseudo-linear time ($O(\alpha n)$ per step amortised; where α is Ackermann⁻¹)

$G_{\odot}$ is convincing model of computation

Linear space

a $G_{\odot}$ -reduction R from $\boxed{t}$ for some term t uses space $O(n)$ after n steps, since the number of symbols introduced by a step of R is bounded by the size of rhss.

Pseudo-linear time

how to **exhibit** an @-C redex-pattern in termgraph G starting from @-node?

G_{eye} is convincing model of computation

Linear space

a G_{eye}-reduction R from $\boxed{t}$ for some term t uses space $O(n)$ after n steps, since the number of symbols introduced by a step of R is bounded by the size of rhss.

Pseudo-linear time

how to exhibit an @-C redex-pattern in termgraph G starting from @-node? indirection-nodes and edges between them constitute **disjoint-set forest** for **union-find** algorithm. exhibiting @-C corresponds to a **find** (causing **path-compression**). replacement of a lhs by a rhs may give rise to **unions** by uniting trees of indirection nodes, but number bounded by size of rhs.

G_o is convincing model of computation

Linear space

a G_o-reduction R from $\boxed{t}$ for some term t uses space $O(n)$ after n steps, since the number of symbols introduced by a step of R is bounded by the size of rhss.

Pseudo-linear time

how to exhibit an @-C redex-pattern in termgraph G starting from @-node?
indirection-nodes and edges between them constitute disjoint-set forest for union-find algorithm. exhibiting @-C corresponds to a find (causing path-compression). replacement of a lhs by a rhs may give rise to unions by uniting trees of indirection nodes, but number bounded by size of rhs.

illustrated next by run for running example 22 (naïve stacking union)

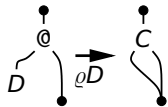
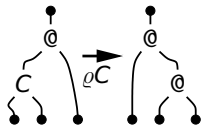
A constructor-unsharing run on $C(D z_1, D z_1) z_2$

👁 rules:

$$\varrho_C(x_0, x_1, x_2) : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$

$$\varrho_D(x_0) : D x_0 \rightarrow C(x_0, x_0)$$

G👁 rules:

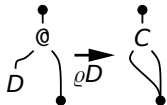
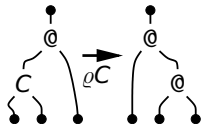


👁 rules:

$$\varrho_C(x_0, x_1, x_2) : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$

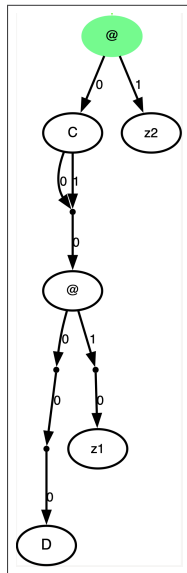
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G👁 rules:



term:

$$C(D z_1, D z_1) z_2$$

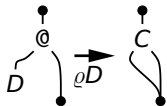
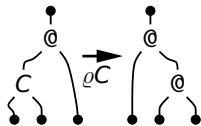


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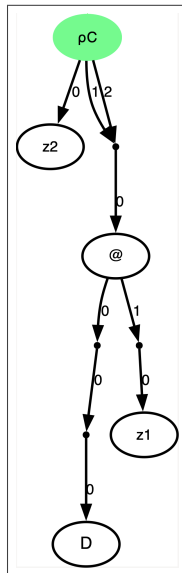
$$\varrho_D(x_0) : D x_0 \rightarrow C(x_0, x_0)$$

G👁 rules:



family step:

$$\varrho_C(z_2, D z_1, D z_1) : C(D z_1, D z_1) z_2 \dashv\dashv D z_1 (D z_1 z_2)$$

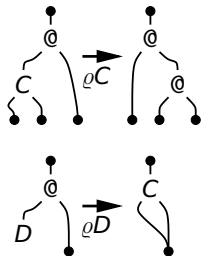


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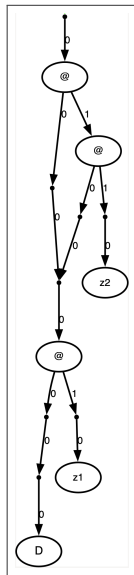
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Go rules:



term:

$$D z_1 (D z_1 z_2)$$

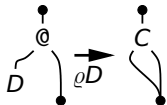
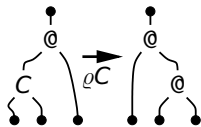


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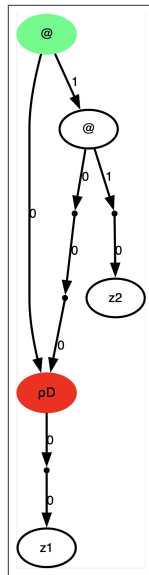
$$\varrho_D(x_0) : D x_0 \rightarrow C(x_0, x_0)$$

G👁 rules:



family step:

$$\varrho_D(z_1) (\varrho_D(z_1) z_2) : D z_1 (D z_1 z_2) \dashv\dashv C(z_1, z_1) (C(z_1, z_1) z_2)$$

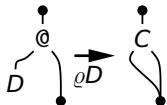
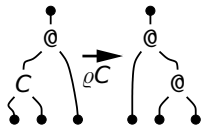


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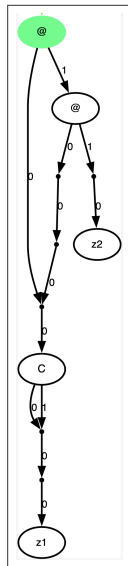
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G👁 rules:



term:

$$C(z_1, z_1) (C(z_1, z_1) z_2)$$

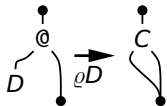
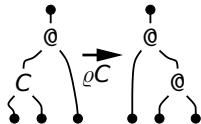


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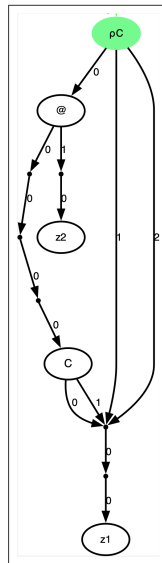
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G👁 rules:



family step:

$$\varrho_C(C(z_1, z_1) z_2, z_1, z_1) : \textcolor{red}{C}(z_1, z_1) (C(z_1, z_1) z_2) \dashv\vdash z_1 (z_1 (C(z_1, z_1) z_2))$$

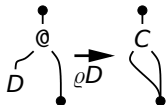
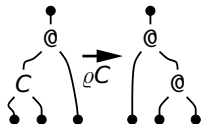


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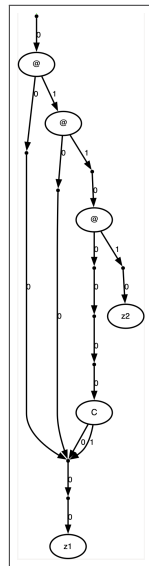
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G👁 rules:



term:

$$z_1 (z_1 (C(z_1, z_1) z_2))$$

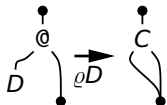
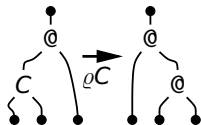


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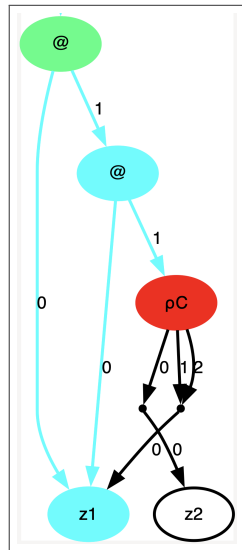
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G👁 rules:



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$$z_1 (z_1 \varrho_C(z_2, z_1, z_1)) : z_1 (z_1 (C(z_1, z_1) z_2)) \dashv\vdash z_1 (z_1 z_1 (z_1 z_2))$$

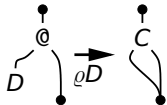
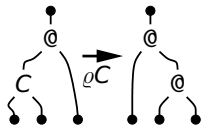


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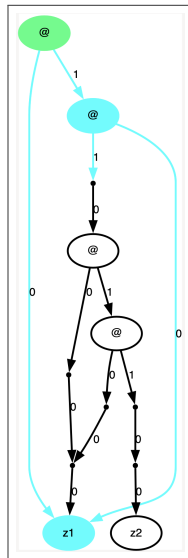
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$$z_1 (z_1 z_1 (z_1 z_2))$$

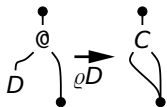
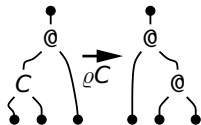


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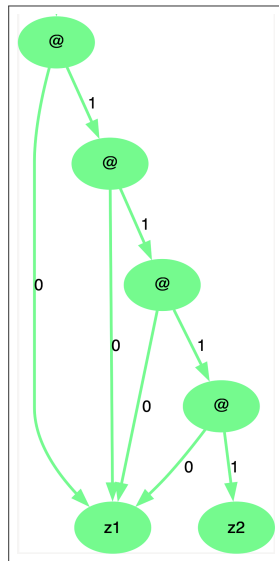
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Steps as structures (Terese 03)

Idea for representation of steps

- rewrite steps as **structures** themselves in **structure**-rewriting
- **objects** (**steps**) as structures over signature of **function** (and **rule**) symbols
- src / tgt by **homomorphism** mapping rule symbols to lhs / rhs

Steps as structures

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- objects (steps) as structures over signature of function (and rule) symbols
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Example (term rewrite step as term)

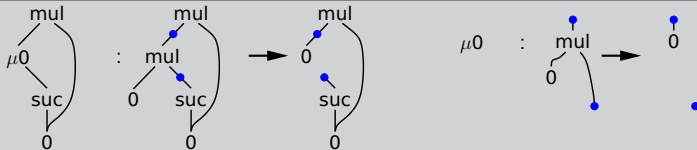
- $\varrho_D(z_1) (\varrho_D(z_1) z_2)$ is **term** representing (parallel) **term** rewrite step
- term over **function** symbols $@, D, C$ and **rule** symbol ϱ_D
- source $D z_1 (D z_1 z_2)$ / target $C(z_1, z_1) (C(z_1, z_1) z_2)$ by mapping ϱ_D in step to lhs $D x_0$ / rhs $C(x_0, x_0)$ for rule $\varrho_D(x_0) : D x_0 \rightarrow C(x_0, x_0)$

Steps as structures

Idea for representation of steps

- rewrite steps as structures themselves in structure-rewriting
- objects (steps) as structures over signature of function (and rule) symbols
- src / tgt by homomorphism mapping rule symbols to lhs / rhs

Example (termgraph rewrite step as termgraph)



step as **termgraph** over function symbols mul , suc , 0 and rule symbol $\mu 0$

Steps as structures

Idea for representation of steps

- rewrite steps as structures themselves in structure-rewriting
- objects (steps) as structures over signature of function (and rule) symbols
- src / tgt by homomorphism mapping rule symbols to lhs / rhs

Canonicity of representation

canonical (concrete) way of representing steps based on **homomorphism**
no extra-curricular *ad hoc* choices (contexts, substitutions, positions, ...)

Steps as structures

Idea for representation of steps

- rewrite steps as structures themselves in structure-rewriting
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Canonicity of representation

canonical (concrete) way of representing steps based on homomorphism
no extra-curricular *ad hoc* choices (contexts, substitutions, positions, ...)

my experience: works well across the board (theory, proofs, implementation)
e.g., prove properties of **term** rewrite steps by induction on **terms**, and
in formalisation **build step** properties on **term** properties (TRS Kirk & Middeldorp)

Who's your family depends on the way of creation

Family intuition (Lévy 78)

given a reduction $R : t_0 \rightarrow t_1 \rightarrow \dots$ two redex-pattern occurrences in t_i belong to the same **family** if they have the same **creation history**.

that's vague, so Lévy gave 3 **characterisations** via **labelling**, **zig-zag**, **extraction**
he would have preferred 4th via **sharing** in graph rewriting (Lamping, Kathail 90)

Who's your family depends on the way of creation

Definition (Family for a given graph implementation)

for graph reduction $R : \boxed{t_0} =: G_0 \rightarrow G_1 \rightarrow \dots$ redex-pattern occurrences in **term**
 $t_i := \widehat{G}_i$ in $\widehat{R} : \widehat{G}_0 \rightarrow \widehat{G}_1 \rightarrow \dots$ in **same family** if represented by **same** in **graph** G_i

Who's your family depends on the way of creation

Definition (Family for a given graph implementation)

for graph reduction $R : \boxed{t_0} =: G_0 \rightarrow G_1 \rightarrow \dots$ redex-pattern occurrences in term $t_i := \widehat{G}_i$ in $\widehat{R} : \widehat{G}_0 \multimap \widehat{G}_1 \multimap \dots$ in same family if represented by same in graph G_i

idea: shared redex-pattern occurrences **share** their creation-history

history-dependent: a in $f(a, a) \rightarrow f(a, a)$ for rules $a \rightarrow \dots$ and $f(x, y) \rightarrow f(x, x)$??

OGTRS / G_{eye} **termgraphs**: only **horizontal** sharing so $\multimap$ -steps in fact $\multimap$ steps

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Example

D -redex-pattern occurrences in same family in running example run (page 16)

$\varrho_D(z_1) (\varrho_D(z_1) z_2) : D z_1 (D z_1 z_2) \multimap C(z_1, z_1) (C(z_1, z_1) z_2)$

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Example

a 's in same family in s , but not in same family in t in

$t := f(\textcolor{red}{a}, \textcolor{blue}{a}) \rightarrow f(\textcolor{red}{a}, \textcolor{red}{a}) =: s$ in sharing TGRS, for rules $a \rightarrow \dots$ and $f(x, y) \rightarrow f(x, x)$

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Example (family depending on notion of reduction, implementation)

let $M := (\lambda x.x (x \mathfrak{S})) \lambda y.N$, where N is some (closed) redex, say $\mathfrak{I} \mathfrak{K}$

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Who's your family depends on the way of creation

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after $M \rightarrow (\lambda y.N) ((\lambda y.N) \mathfrak{S}) \rightarrow (\lambda y.N) N =: L$, should occurrences of N be shared?
(yes) for β -steps implemented through **sharing graphs**; Lamping 90:
contraction of $(\lambda y.N) \mathfrak{S}$ keeps **redex** N shared in L
the **white box** of the function $\lambda y.N$ is **opened** in 2nd graph step

Who's your family depends on the way of creation

Definition (Family for a given graph implementation)

for graph reduction $R : \boxed{t_0} =: G_0 \rightarrow G_1 \rightarrow \dots$ redex-pattern occurrences in term $t_i := \widehat{G}_i$ in $\widehat{R} : \widehat{G}_0 \rightarrow \widehat{G}_1 \rightarrow \dots$ in same family if represented by same in graph G_i

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(no) for $\bar{\beta}$ -steps implemented through **termgraphs** $G \odot$:
contraction of $(\lambda y. N) \mathfrak{S}$ **unshares** (the constructor representing) **function** $\lambda y. N$
the function $\lambda y. N$ is **black box** (constructor) **hiding** redex N in termgraph of L

Who's your family depends on the way of creation

Definition (Family for a given graph implementation)

for graph reduction $R : \boxed{t_0} =: G_0 \rightarrow G_1 \rightarrow \dots$ redex-pattern occurrences in term $t_i := \widehat{G}_i$ in $\widehat{R} : \widehat{G}_0 \multimap \widehat{G}_1 \multimap \dots$ in same family if represented by same in graph G_i

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upshot: **family** is **intensional** property depending on rules; from just the **step**
 $f(a) \rightarrow f(a, a)$ can't tell whether a 's in same family in $f(a, a)$ or not

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upshot: family is intensional property depending on rules; from just the step $f(a) \rightarrow f(a, a)$ can't tell whether a 's in same family in $f(a, a)$ or not
for rule $f(a) \rightarrow f(a, a)$ **no**, but for rule $f(x) \rightarrow f(x, x)$ **yes**

Who's your family depends on the way of creation

Definition (Family for a given graph implementation)

for graph reduction $R : \boxed{t_0} =: G_0 \rightarrow G_1 \rightarrow \dots$ redex-pattern occurrences in term $t_i := \widehat{G}_i$ in $\widehat{R} : \widehat{G}_0 \multimap \widehat{G}_1 \multimap \dots$ in same family if represented by same in graph G_i

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upshot: family is intensional property depending on rules

induced by **residuals** of redex-patterns (Church & Rosser 36, Newman 42, ...)

residuals factor through **descendants** of symbols (Morris, $\mathbb{V}$ proofterm algebra)

Who's your family depends on the way of creation

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induced by residuals of redex-patterns (Church & Rosser 36, Newman 42, ...)

residuals factor through descendants of symbols (Morris, $\mathbb{V}$ proofterm algebra)

slogan: tell me your reduction history and rules, and i'll tell you your family

Random descent for $G\hookrightarrow$

Theorem (in essence Staples 80)

$G\hookrightarrow$ has *random descent* (Newman 42, $\forall$ 07): if G reduces to a normal form, then G is *complete* (confluent and terminating) and all reductions from G end in the same normal form, in the same number of steps

Random descent for $G\odot$

Theorem (in essence Staples 80)

$G\odot$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Proof.

$G\odot$ is constructor-unsharing and **orthogonal**. redex-pattern occurrences are **non-overlapping** and **commute directly**: $\leftarrow \cdot \rightarrow \subseteq = \cup (\rightarrow \cdot \leftarrow)$ then by $\forall$ 07 $\square$

termgraph rewriting is **linear**; term rewriting is **replicating**

Random descent for $G\circlearrowright$

Theorem (in essence Staples 80)

$G\circlearrowright$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Corollary

$G\circlearrowright$ reduction is *optimal* (if normal form exists, reached in *least* number of steps)

trivially so by random descent; one can *descend randomly* toward normal form

Random descent for $G\textcircled{e}$

Theorem ()

$G\textcircled{e}$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Corollary

$G\textcircled{e}$ reduction is optimal

Caveat

$G\textcircled{e}$ reduction to normal form includes reduction inside **garbage**

Random descent for $G\text{eye}$

Theorem ()

$G\text{eye}$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Caveat

$G\text{eye}$ reduction to normal form includes reduction inside garbage

Example

for rule $f(x) \rightarrow a$, normalising termgraph $\boxed{f(t)}$ in TGRS requires normalising t , though t could be garbage collected after $\boxed{f(t)} \rightarrow a$ (**unreachable** from root)

Random descent for $G\textcircled{e}$

Theorem ()

$G\textcircled{e}$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Lemma

leftmost-outermost reduction $\rightarrow_{lmo}$ is **optimal** for reduction to **rrnf**
(**root-reachable** normal form; subgraph reachable from root in normal form)

Random descent for $G\textcircled{e}$

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$G\textcircled{e}$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Lemma

leftmost-outermost reduction $\rightarrow_{lmo}$ is optimal for reduction to *rrnf*

Proof.

$\rightarrow_{lmo}$ is **better** than $\rightarrow$ by OLCOM($\rightarrow_{lmo}, \rightarrow$): $lmo \leftarrow \cdot \rightarrow \subseteq = \cup (\rightarrow^= \cdot lmo \leftarrow)$ $\square$

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ordered local commutation ($\textcircled{V}$ 07) for comparing strategies by local peaks
at ISR 2017 for program improvement; reinvented by Hamana & Muroya 24

Random descent for $G\hookrightarrow$

Theorem ()

$G\hookrightarrow$ has random descent: if G reduces to a normal form, then G is complete and all reductions from G end in the same normal form, in the same number of steps

Lemma

leftmost-outermost reduction $\rightarrow_{lmo}$ is optimal for reduction to rrnf

Proof.

$\rightarrow_{lmo}$ is better than $\rightarrow$ by $OLCOM(\rightarrow_{lmo}, \rightarrow)$: $lmo \leftarrow \cdot \rightarrow \subseteq = \cup (\rightarrow^= \cdot lmo \leftarrow)$ $\square$

next: lmo known to have good properties on terms; what about on termgraphs?

Pseudo-linearity of the leftmost–outermost strategy

Contraction vs. Finding

nice that redex-patterns can be exhibited and contracted in (pseudo-)linear time, but what about selecting and finding them?

Pseudo-linearity of the leftmost–outermost strategy

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question **because** TRS / TGRS **causal** MoC unlike **sequential** TMs, determining the **next** thing to do may not be immediate from the **previous** thing done

Pseudo-linearity of the leftmost–outermost strategy

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question because TRS / TGRS causal MoC unlike sequential TMs, determining the next thing to do may not be immediate from the previous thing done
selection is governed by **strategy** whose **complexity** reflects how complex following it is (**finding** redex-pattern according to the strategy)

Pseudo-linearity of the leftmost–outermost strategy

Definition (for rewrite system $\rightarrow$)

strategy is a subsystem of $\rightarrow$ having same sets of objects and normal forms as $\rightarrow$
don't allow to stop computation prematurely; no change of semantics

Pseudo-linearity of the leftmost–outermost strategy

Definition (for rewrite system $\rightarrow$)

strategy is a subsystem of $\rightarrow$ having same sets of objects and normal forms as $\rightarrow$

Lemma

leftmost–outermost (lmo) strategy is pseudo-linear in length of reduction for $G\odot$

for $G\odot$ normal form s has shape $C(\vec{s})$ or $x\vec{s}$ for normal forms $\vec{s}$

Pseudo-linearity of the leftmost–outermost strategy

Definition (for rewrite system $\rightarrow$)

strategy is a subsystem of $\rightarrow$ having same sets of objects and normal forms as $\rightarrow$

Lemma

lmo strategy is pseudo-linear in length of reduction for $G\odot$

Proof idea (exploit locality of causality in graph rewriting / $G\odot$; diff).

implementable by **dipper** data-structure dipping down the **head-spine** toward a constructor or variable, contracting redex-patterns, followed by proceeding **recursively** along **subterms** $\vec{t}$ (for $C(\vec{t})$) or **vertebrae** $\vec{t}$ (for $x\vec{t}$)

Pseudo-linearity of the leftmost–outermost strategy

Definition (for rewrite system $\rightarrow$)

strategy is a subsystem of $\rightarrow$ having same sets of objects and normal forms as $\rightarrow$

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lmo strategy is pseudo-linear in length of reduction for $G\odot$

Proof idea (exploit locality of causality in graph rewriting / $G\odot$; diff).

implementable by dipper data-structure dipping down the head-spine toward a constructor or variable, contracting redex-patterns, followed by proceeding recursively along subterms or vertebrae
linear number of **visits** of symbols other than indirections by dipper, so pseudo-linear by **finding** the arguments of these symbols. □

Properties of lefmost–outermost strategy on G

Leftmost–outermost on terms vs. termgraphs

nice that lmo is pseudo-linear in **termgraph** rewriting, but does it have good properties and if so, do these transfer to **term** rewriting?

Properties of lefmost–outermost strategy on $G\mathcal{O}$

Leftmost–outermost on terms vs. termgraphs

nice that Imo is pseudo-linear in termgraph rewriting, but does it have good properties and if so, do these transfer to term rewriting?

e.g., is Imo (hyper-)((weak) head-)normalising on $G\mathcal{O}$?

if so, does that transfer to the same for $\mathcal{O}$?

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reductionist idea: exploit Imo is (hyper-)((weak) head-)normalising on $\mathcal{O}$ and on β because they are left-normal orthogonal PRSs.

Properties of lefmost–outermost strategy on $G\textcircled{\bullet}$

reductionist idea: exploit Imo is (hyper-)((weak) head-)normalising on $\textcircled{\bullet}$ and on β because they are left-normal orthogonal PRSs.

family step for a redex-pattern does **at least as much as step**; specialises to Imo :

Lemma

*if $\Phi : G \rightarrow H$ is **Imo** in $G\textcircled{\bullet}$, then family step $\hat{\Phi} : \hat{G} \dashv\dashv \hat{H}$ contracts the **Imo** redex-pattern in the term $\hat{G}$ (and possibly others)*

Properties of lefmost–outermost strategy on $G\textcircled{\scriptsize\bullet}$

reductionist idea: exploit lmo is (hyper-)((weak) head-)normalising on $\textcircled{\scriptsize\bullet}$ and on β because they are left-normal orthogonal PRSs.

Lemma

if $\Phi : G \rightarrow H$ is lmo in $G\textcircled{\scriptsize\bullet}$, then family step $\hat{\Phi} : \hat{G} \dashrightarrow \hat{H}$ contracts the lmo redex-pattern in the term $\hat{G}$

Corollary

optimal implementation of family reduction of $\bar{\beta}$

lmo family rewriting is optimal among $\dashrightarrow_{\bar{\beta}}$ -family-strategies on λ -terms

Properties of lefmost–outermost strategy on $G\textcircled{\text{e}}$

reductionist idea: exploit Imo is (hyper-)((weak) head-)normalising on $\textcircled{\text{e}}$ and on β because they are left-normal orthogonal PRSs.

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Corollary

Imo closed β -reduction ($\bar{\beta}$) to (weak head) normal form implemented by $G\textcircled{\text{e}}$ in space linear and time pseudo-linear in length of the reduction

Properties of lefmost–outermost strategy on $G\textcircled{\text{e}}$

reductionist idea: exploit Imo is (hyper-)((weak) head-)normalising on $\textcircled{\text{e}}$ and on β because they are left-normal orthogonal PRSs.

Corollary

Imo weak β -reduction ($\tilde{\beta}$) to (weak head) normal form implemented by $G\textcircled{\text{e}}$ in space linear and time pseudo-linear in length of the reduction

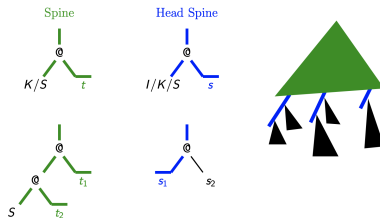
Generalising from **Imo** to **spine** strategies for

Spine strategy

Definition

Spine: if head normal form recur, else **Head Spine**.

Head Spine: recur on left.



Example

$S(SISI)(K(IK))$

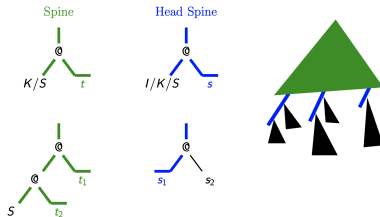
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Lemma

Every term not in normal form has Spine redex

Generalising from Imo to spine strategies for

Definition (of spine for -terms)

- spine: t or $x t_1 \dots t_n$ or $C(t_1, \dots, t_n)$
- head spine: x or $C(t_1, \dots, t_n)$ or $t s$

Generalising from Imo to spine strategies for

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Lemma (normalising strategy)

- *every term not in normal form has redex-pattern on **spine**, so a **strategy***
- *spine strategy is a **normalising** strategy having random descent*

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Lemma (normalising strategy)

- *every term not in normal form has redex-pattern on **spine**, so a **strategy***
 - *spine strategy is a **normalising** strategy having random descent*
-
- **random descent**: reductions to normal form have same length / measure
 - **leftmost-outermost** strategy is a **spine**-strategy

Part II: Implementing through termgraphs G

Summary of Part II

- constructor-unsharing (cu) termgraph rewriting $G$ is a **convincing** causal (asynchronous) **model of computation**
- **Imo** family- $\multimap_{\tilde{\beta}}$ **optimal (needed)** for family- $\multimap_{\tilde{\beta}}$ on λ -terms
- **closed** ($\tilde{\beta}$) and **weak** ($\tilde{\beta}$) reduction of λ -terms can be **implemented** by compiling to termgraph rewriting $G$, **factoring** through term rewriting 
- any **spine family** strategy is (weakly head) normalising and can be implemented in **linear space** and **pseudo-linear time** through **spine** in $G$

Part II: Implementing $\hookrightarrow$ through termgraphs $G\hookrightarrow$

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- constructor-unsharing (cu) termgraph rewriting $G\hookrightarrow$ is a convincing causal (asynchronous) model of computation
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what about implementing (full) β itself?

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- any spine family strategy is (weakly head) normalising and can be implemented in linear space and pseudo-linear time through spine in $G\hookrightarrow$

what about implementing (full) β itself? next up

idea: **factor** through special spine reduction $G\hookrightarrow$, adjoining explicit α

Factoring β through $\tilde{\beta}$ and explicit α

Idea for (full) β

if **head-spine** is a constructor $C(t_1, \dots, t_n)$ then some β -redexes may be **hidden** by C . then **decompile** C . can be implemented for $\odot$ by **printing** λx for x **fresh**, then **recursively** compute $C(t_1, \dots, t_n) x$

factoring β through $\tilde{\beta}$ old idea: De Bruijn, Coquand, Grégoire & Leroy

Factoring β through $\tilde{\beta}$ and explicit α

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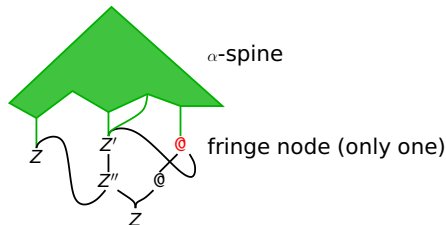
Caveat for termgraphs

if constructor is **shared** it may be head-spine for one but non-head-spine for others. risk of premature decompilation (unsharing; breaking space linearity)

Termgraph α -spine strategy

Definition (of (head / α -)spine nodes)

- **spine**: **head spine**, or such in normal form (**hsnf**) with **spine** vertebrae
- **head spine**: path from root through bodies of @,• to variable or constructor
- α -**spine**: **spine** prefix; **fringe** nodes: nodes **covered** by α -spine



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Lemma

*every termgraph not in normal form has a **spine** redex-pattern, and any (proper) α -**spine** prefix of it has a non-empty fringe*

Proof.

by minimality using acyclicity of termgraphs



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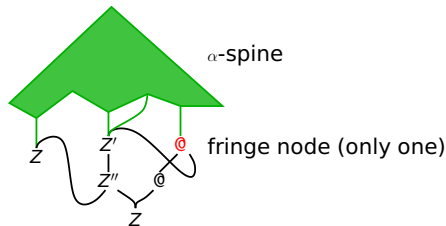
reduce **head spines** from fringe nodes to **hsnf** and recurse on **spine** vertebrae

by lemma always some step possible until whole termgraph is **α -spine** (in nf)

Termgraph α -spine strategy **adapted** to spine- β

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Termgraph α -spine strategy **adapted** to **spine- β**

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Definition (of α -spine strategy)

reduce **head spines** from fringe nodes to **hsnf** and recurse on **spine** vertebrae
rewrite fringe constructor $C(t_1, \dots, t_n)$ **to** $\lambda x.C(t_1, \dots, t_n) x$ **for** x **fresh**

idea: a combinator on fringe / α -spine **is** a λ -abstraction (in the β -nf), so may **recurse** on its body, effectuated in $\odot$ by supplying a fresh variable

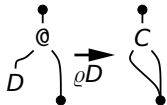
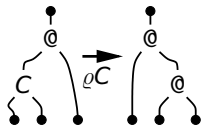
Example α -spine reduction (Java code $\Rightarrow$ dot $\Rightarrow$ graphs)

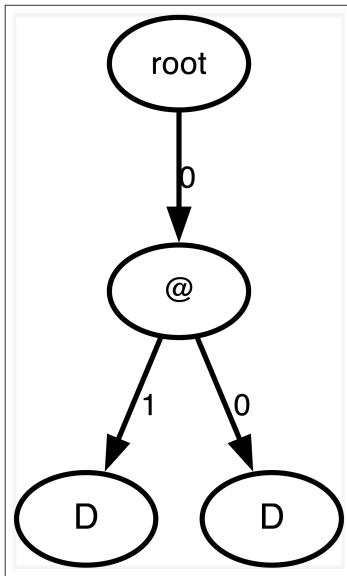
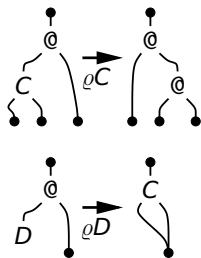
recall $\odot$ -rules:

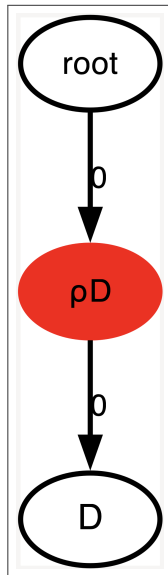
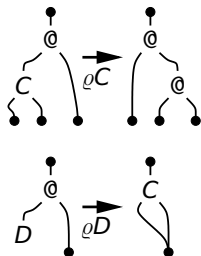
$$\varrho_C : C(x_1, x_2) x_0 \rightarrow x_1 (x_2 x_0)$$

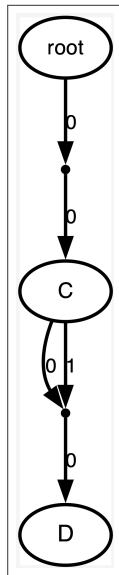
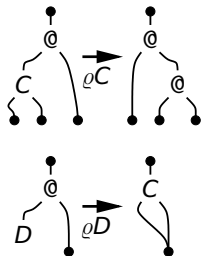
$$\varrho_D : D x_0 \rightarrow C(x_0, x_0)$$

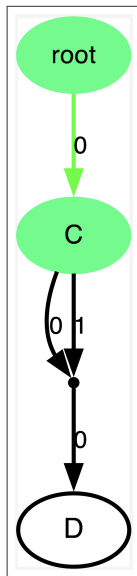
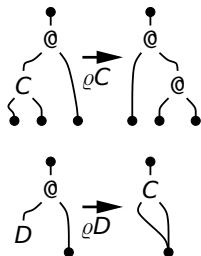
and termgraph rules:





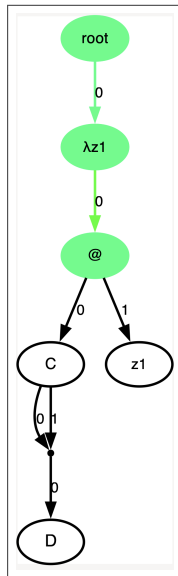


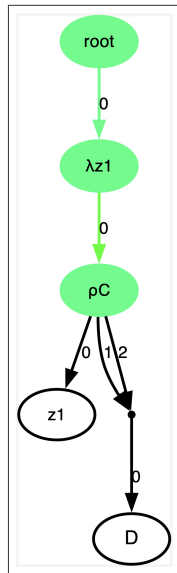
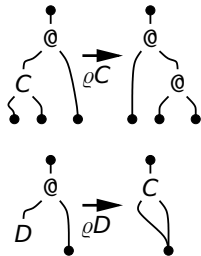


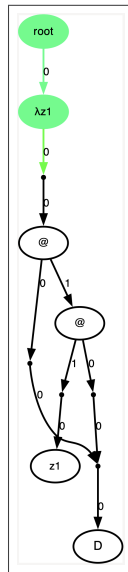
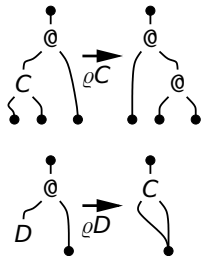


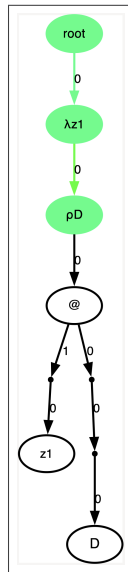
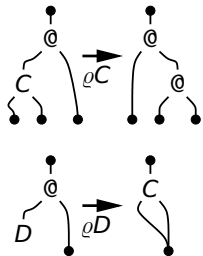


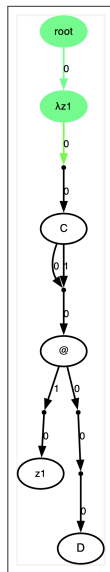
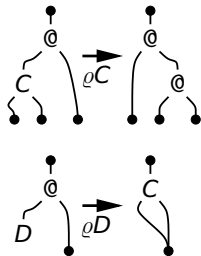
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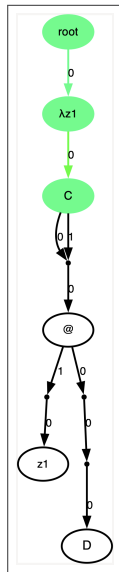
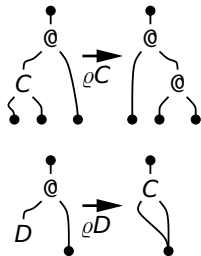


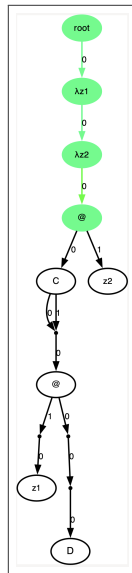
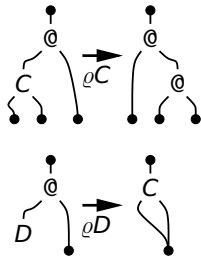












Implementing some **spine**- β -strategy via

Observations

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- cost of constructor-steps bounded by size of final term

Implementing some **spine**- β -strategy via

Corollary

*results for $\tilde{\beta}$ carry over to **spine**- β . the cost of reduction to β -normal form is **(pseudo)-linear** in the number of leftmost-outermost β -steps to β -nf*

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Reductionist view

- refactor Wadsworth through OTRS  and constructor-unsharing OTGRS G  (Balabonski PhD)
- refactor theory and cost analysis for $\tilde{\beta} / \bar{\beta}$ through (left-normal) OTRS theory
- refactor theory for $\text{Imo } \beta$ and costs analysis through $\tilde{\beta}$
- refactor notion through graph rewriting
- refactor structure-rewriting through substitution calculus

Springtime for interaction nets!

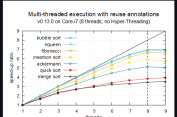
Inpla: Interaction nets as a programming language

What is Inpla

Inpla is a multi-threaded parallel interpreter of interaction nets. Once you write programs for sequential execution, it works also in multi-threaded parallel execution. Each thread is managed on each CPU-core with POSIX-thread library.

- The current version is 0.13.0-2, released on 12 September 2024. (See [Changelog](#) for details.)
- The below graph shows speed-up ratio to threads numbers for programs in the following benchmark table.

Multi-threaded execution with reuse annotations
v0.13.0 on Core2 (8 threads, no Hyper-Threading)



github.com/inpla/inpla

The Vine Programming Language

Vine is an experimental new programming language based on interaction nets.

Vine is a multi-paradigm language, featuring seamless interop between functional and imperative patterns.

See [vine/examples/](#) for examples of Vine.

```
cargo run -- --bin vine run vine/examples/DNRE.vi
```

If you're curious to learn more, join the [Vine Discord server](#).

(Vine is still under heavy development; many things will change.)

vine.dev

Higher Order Company

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THE PARALLEL
FUTURE OF COMPUTATION*

SEND
A PARALLEL LANGUAGE

With Babel you can write parallel code for multi-core CPUs/GPUs without being a C/CUDA expert with 10 years of experience. It feels just like Python!

No need to deal with the complexity of concurrent programming: locks, mutexes, atomics... any work that can be done in parallel will be done in parallel.

```
from itertools import repeat
def compute(x):
    return x * x
def main():
    n = 1000000
    for i in range(1, n+1):
        compute(i)
    return 0
```

Example Programs
Simple Parallel Sort

[Try it Now!](#)

higherorderco.com

Optiscope

Optiscope is an experimental Lévy-optimal implementation of the pure lambda calculus enriched with native function calls, if-then-else expressions, & a fixed-point operator.

Being the first public implementation of [Lambdascope](#) ^[1] written in portable C99, it is also the first interaction net reducer capable of calling user-provided functions at native speed. As such, this combination allows one to interleave lazy evaluation with side effects, without resorting to external machinery like monads or algebraic effect handlers. In potential, Optiscope could stand as an optimal system for problems exhibiting vast sharing opportunities & computational intensity.

In what follows, we briefly explain what it means for reduction to be Lévy-optimal, & then describe our results.

github.com/etiams/optiscope